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## Radio link provided compensation of ionosphere and troposphere measurement errors

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## Initial data



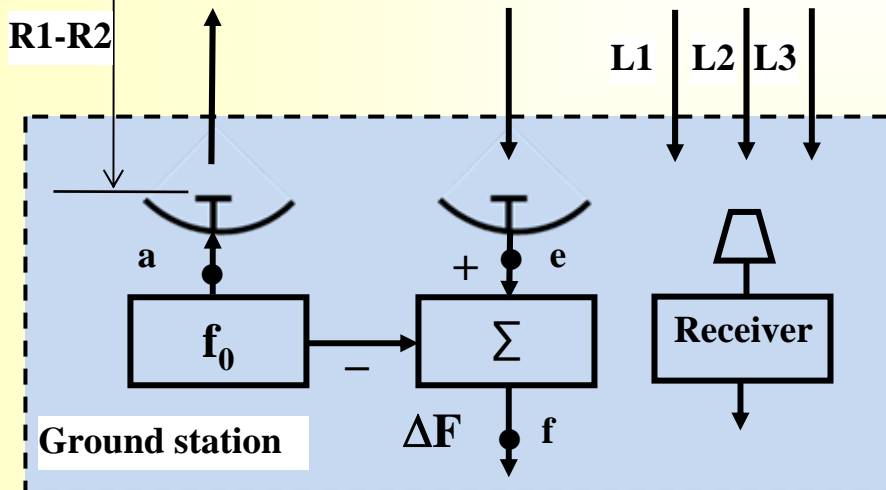
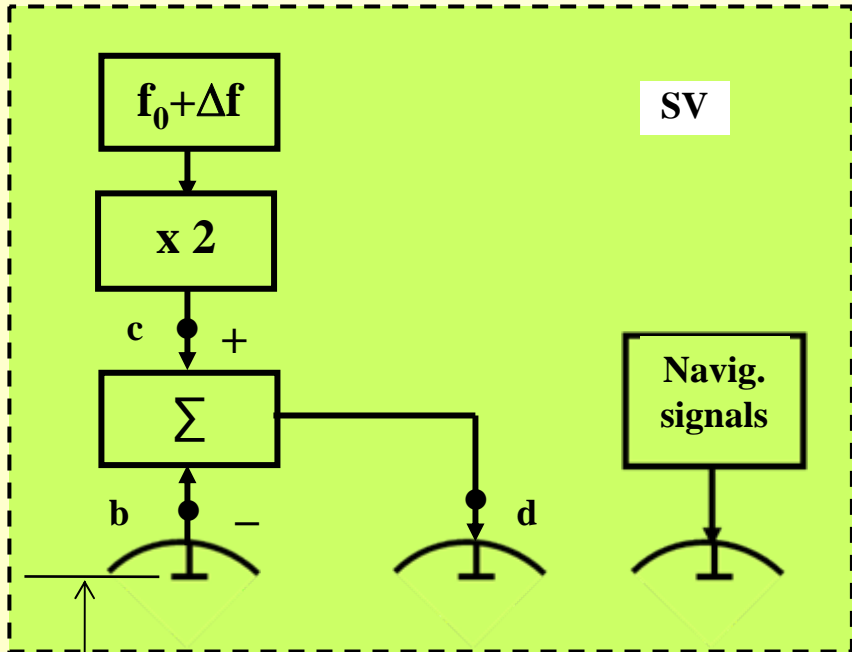
**1. The high stable onboard oscillator is necessary**

**2. Association of compensating radio link with one side (down) radio links in other ranges is expedient**

**3. Such conditions can be easily executed in onboard navigation SV, if the compensating mode is stipulated in a control radio link**

**4. Time of atmospheric fluctuations correlation is more than a signal transmission time**

**5. Fluctuations are caused by movement irregularity in atmosphere**



$$f_a = f_0; \quad f_b = f_0 \left( \frac{1 - \dot{R}/c}{\sqrt{1 - \left(\frac{V}{c}\right)^2 + 2\Phi}} \right)$$

$$f_c = 2(f_0 + \Delta f) \quad f_d = f_c - f_b$$

$$f_e = f_d \left( \frac{\sqrt{1 - \left(\frac{V}{c}\right)^2 + 2\Phi}}{1 + \dot{R}/c} \right)$$

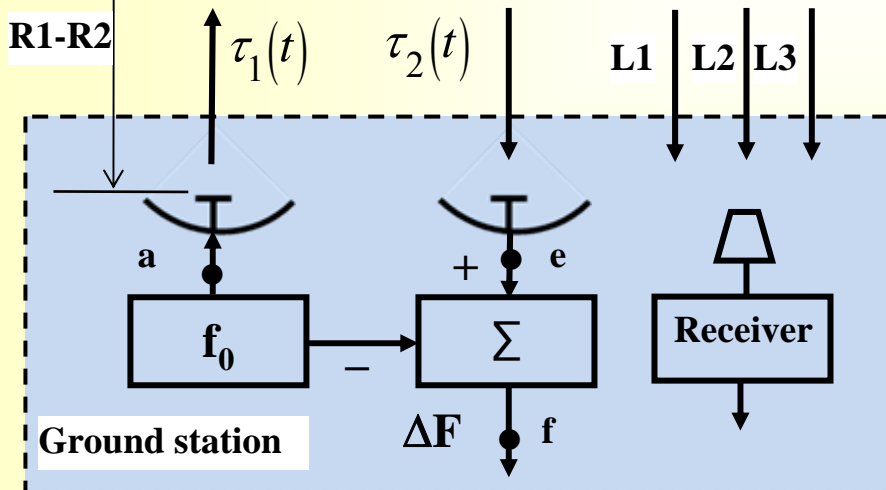
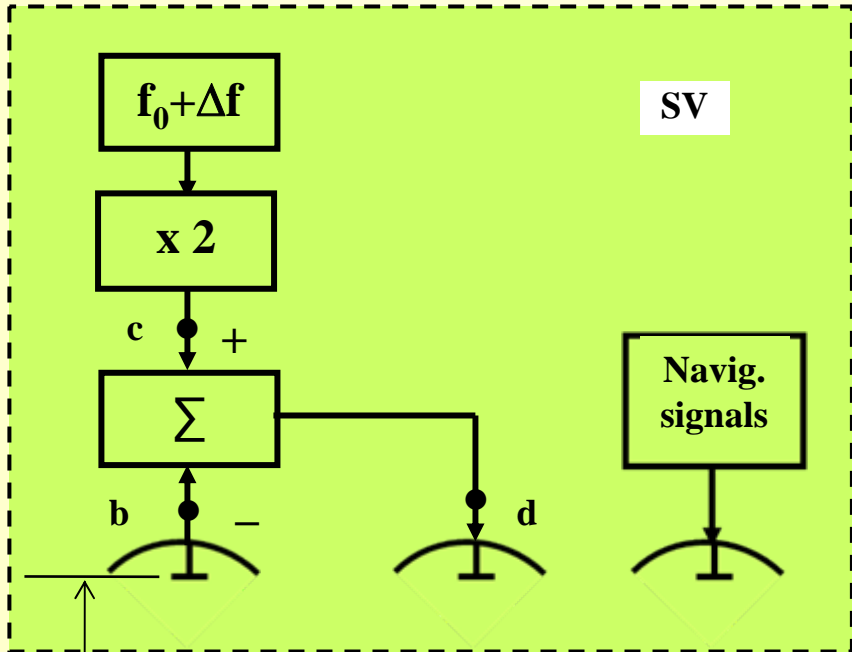
$$\Delta F = f_r = f_e - f_0; \quad \Delta F \approx f_0 \left( 2\Phi - \frac{V^2}{c^2} \right) + 2\Delta f$$

Measured frequency  $\Delta F$  doesn't contain first order Doppler frequency

$$\Phi = \frac{\varphi_a - \varphi_b}{c^2} = \frac{GM_e}{c^2} \left( \frac{1}{R_1} - \frac{1}{R_2} \right)$$

- $V$  – orbital velocity;
- $c$  – velocity of light
- $\Phi$  - difference of ground station-SV gravity potentials
- $G=6,670 \cdot 10^{-8} \text{cm}^3 \text{g}^{-1} \text{s}^{-2}$  - gravitation constant
- $M_e = 5,98 \cdot 10^{27} \text{g}$  – Earth mass
- $R_1, R_2 =$  distance from Earth center to ground station and SV, respectively
- $\dot{R}$  – SV radial velocity

# Compensation of ionosphere and troposphere fluctuations



$$\tau_1 = \tau_0 + \Delta\tau_1(t); \quad \tau_2 = \tau_0 + \Delta\tau_2(t)$$

$$\varphi_f = 2\varphi_0(t - \tau_2) - \varphi_0(t - \tau_1 - \tau_2)$$

$$\Delta\varphi(t) = \omega[\Delta\tau_1(t) - \Delta\tau_2(t)] = \Delta\varphi_1(t) - \Delta\varphi_2(t)$$

$\Delta\varphi_1(t); \Delta\varphi_2(t)$  - phase fluctuation in up- and down- radiolinks, respectively

$$\Delta\tau_2(t) = \Delta\tau_1(t - t_0)$$

$$B_{\Delta\varphi}(l, \theta) = \langle \Delta\varphi(l_1 + l, t + \theta) \cdot \Delta\varphi(l_1, t) \rangle$$

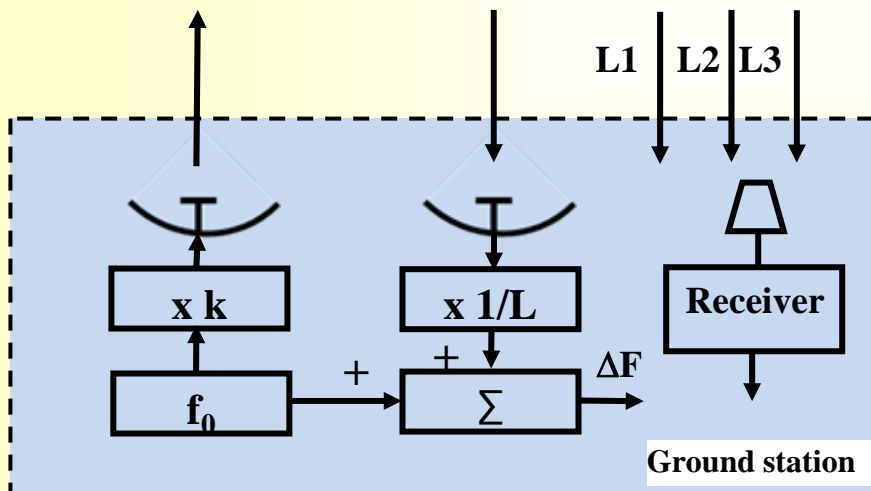
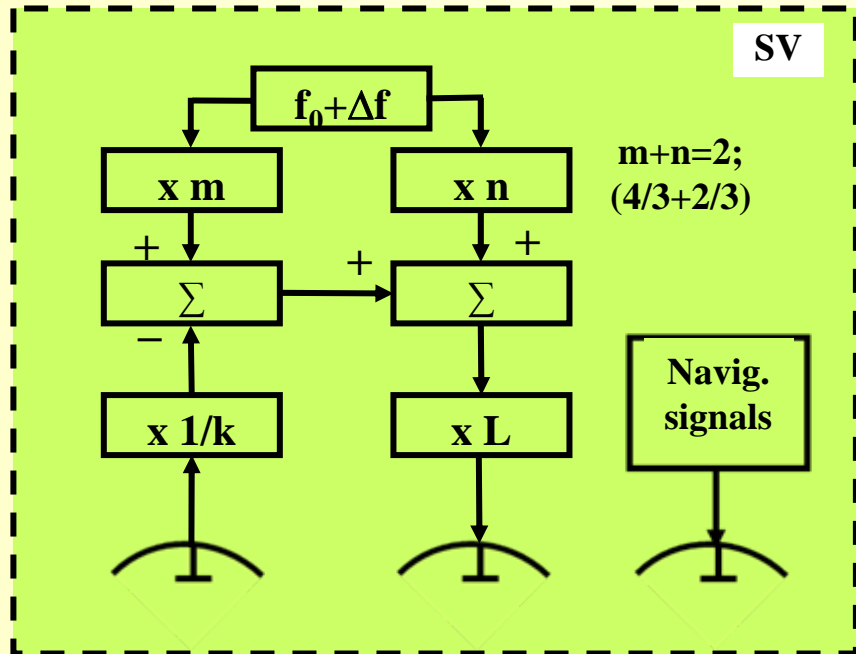
$$= B_{\Delta\varphi}\left(\theta - \frac{l}{V}\right); \quad V - \text{irregularity transfer velocity}$$

$$\overline{\sigma_{\Delta\varphi}^2} = 2\sigma_{\varphi}^2 \left[ 1 + \frac{\theta_k}{2\tau_0} \left( e^{-\frac{2\tau_0}{\theta_k}} - 1 \right) \right]$$

$$\sigma_{\varphi}^2 = 2k^2 \sigma_{\Delta n}^2 l_0 L; \quad k = 2\pi/\lambda; \quad l_0 = V\theta_k$$

$\sigma_{\Delta n}^2$  - refraction coefficient dispersion

L - path length in irregular environment



## Compensation errors:

### •First order Doppler frequency

$$\delta F_d = f_0 \left( 2\Delta\Phi - \frac{\Delta V^2}{c^2} \right); \Delta\Phi \leq 10^{-13} \text{ for } h_{\text{orbit}} \geq 300 \text{ km}$$

$$\Delta V \leq 0.1 \text{ km/s}; \frac{\Delta V^2}{c^2} \leq 10^{-13}; \delta F_d = f_0 \cdot 10^{-13}$$

### •Ionosphere and troposphere fluctuations

$$\delta\phi_{I,T} = 2\sigma_\phi^2 \left[ 1 + \frac{\theta_k}{2\tau_0} \left( e^{-\frac{2\tau_0}{\theta_k}} - 1 \right) \right]$$

#### Quiet troposphere:

$$V = 1 \text{ m/c}; l_0 \approx 60 \text{ m}; \tau_0 \approx 0.07 \text{ s} (R_0 = 2 \cdot 10^4 \text{ km});$$

$$\theta_k = 60 \text{ s}; \delta\phi_T = 2.4 \cdot 10^{-3} \sigma_\phi^2$$

#### Disturbed troposphere: cumulonimbus clouds

$$V = 12 \text{ m/c}; l_0 \approx 6 \text{ m}; \tau_0 \approx 0.07 \text{ s}; \theta_k = 0.5 \text{ s};$$

$$\delta\phi_T = 0.26 \sigma_\phi^2$$

#### Quiet ionosphere:

$$V = 27 \text{ m/c}; l_0 \approx 2 \text{ km}; \tau_0 \approx 0.07 \text{ s}; \theta_k = 75 \text{ s};$$

$$\delta\phi_I = 1.9 \cdot 10^{-3} \sigma_\phi^2$$

#### Disturbed ionosphere: strong solar activity

$$V = 420 \text{ m/c}; l_0 \approx 1 \text{ km}; \tau_0 \approx 0.07 \text{ s}; \theta_k = 2.4 \text{ s};$$

$$\delta\phi_I = 6 \cdot 10^{-2} \sigma_\phi^2$$



## Summary



**The considered radio link can be applied for the various purposes:**

- 1. Measurements of gravitational frequency shift.**
- 2. Compensation of atmospheric fluctuations.**
- 3. Operative frequency control of the onboard frequency standard.**

Listed above functions are realized on the USSR SV Cosmos №97, Cosmos №145 in 1965 – 1967 years.

- 4. Automatic synchronization of the remote generators (onboard - ground, ground - ground, onboard - onboard).**



## References



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2. N.G. Basov, O.N. Krokhin, A.N. Oraevskii, G.M. Strakhovskii, B.M. Chikhachev. Soviet Physics-Uspekhi, 1961, 75, 1, 3.
3. B.M. Chikhachev, N.E. Ivanov, G.M. Fedorenko and others. "Space Research", 1975, v. XIII, 3, p.381.